

# CAMERA. SHAPES. SOUNDS

ART 185GL .XINGHAN LIU

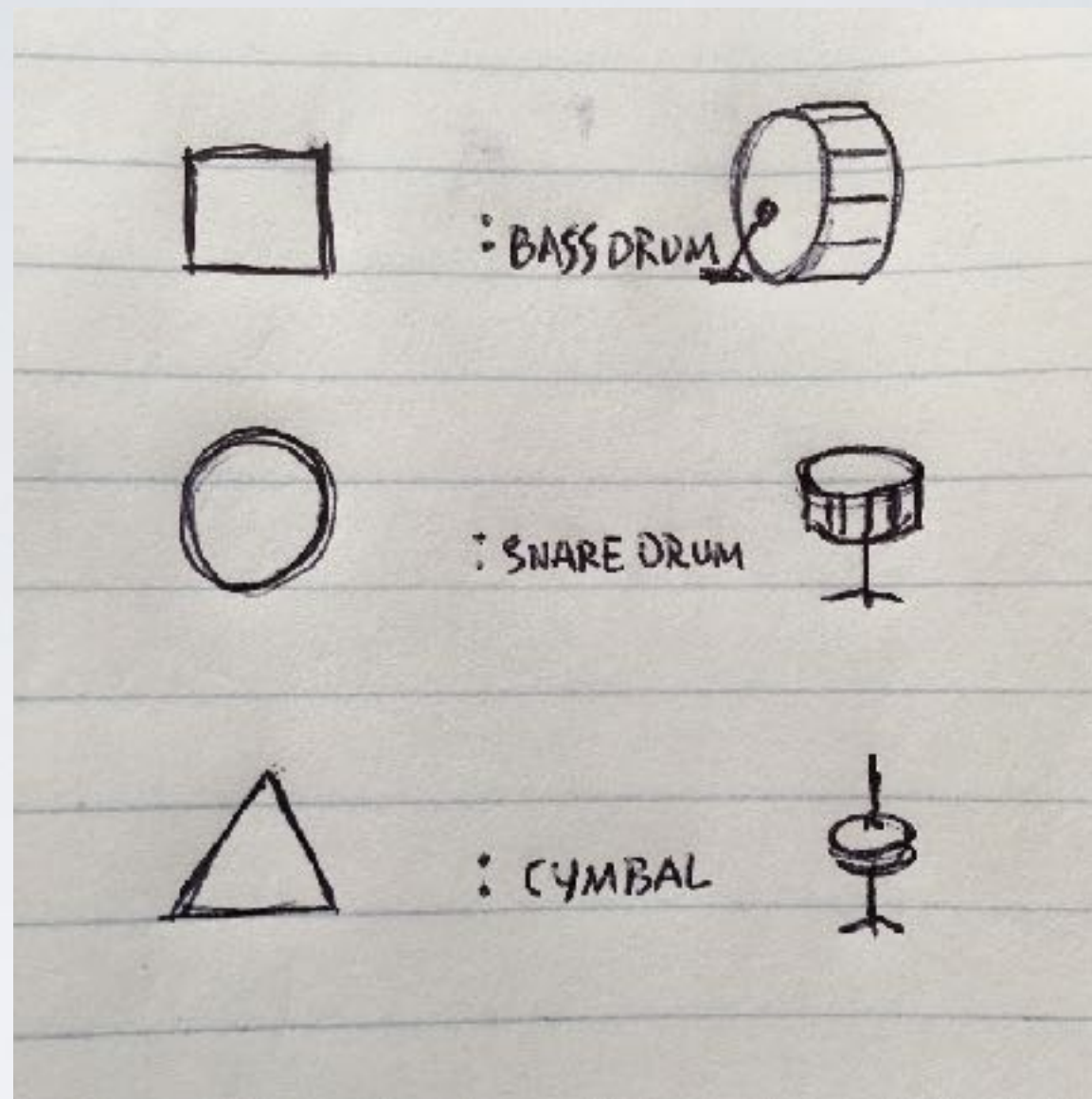


# SHAPE AND MUSIC

Guitar Hero







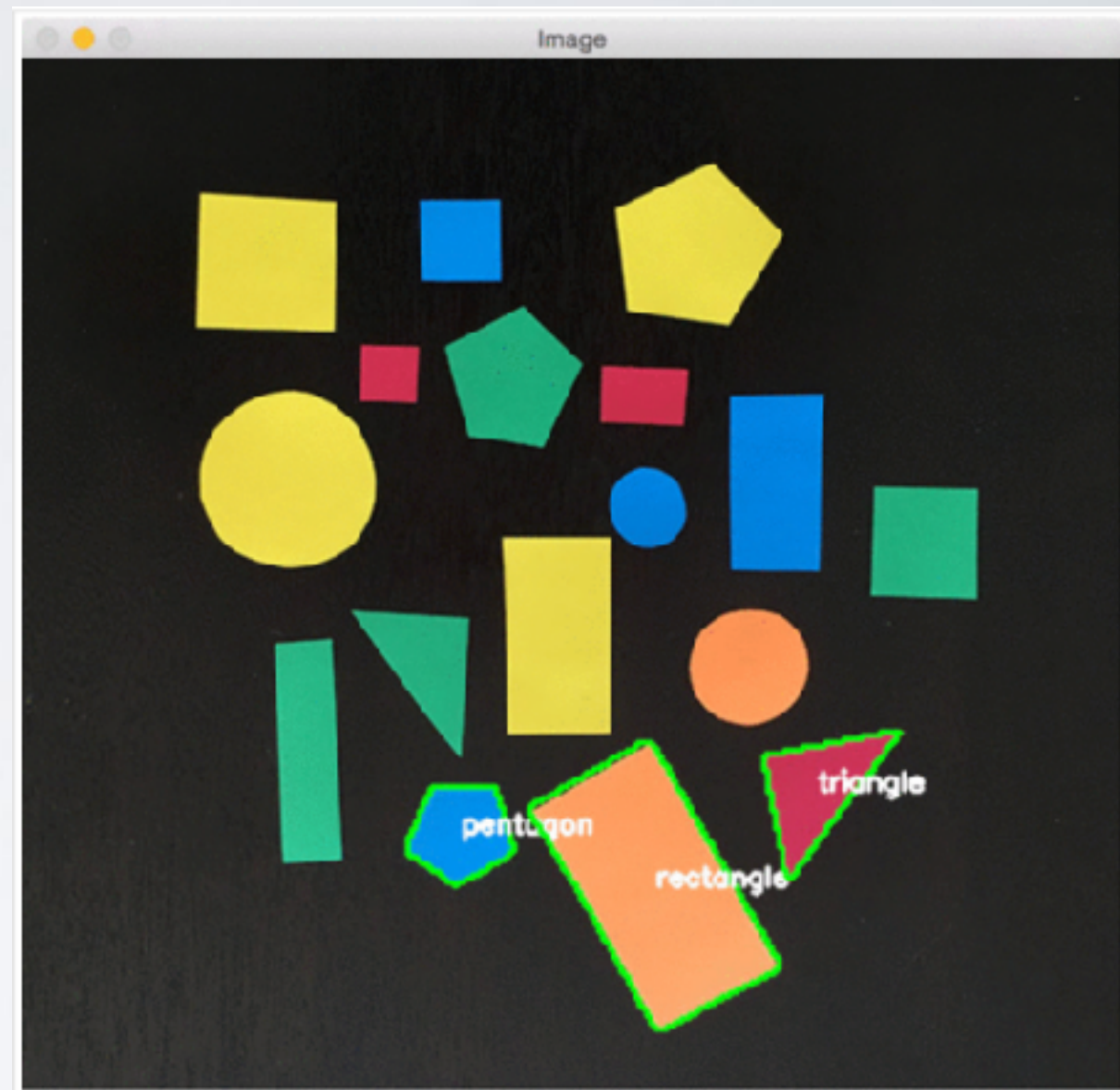
EACH SHAPE REPRESENTS A PART OF THE  
DRUMS

# CAMERA & SHAPE



# OPENCV SHAPE DETECTION

This is my research



```
shapedetector.py
1 # import the necessary packages
2 import cv2
3
4 class ShapeDetector:
5     def __init__(self):
6         pass
7
8     def detect(self, c):
9         # initialize the shape name and approximate the contour
10        shape = "unidentified"
11        peri = cv2.arcLength(c, True)
12        approx = cv2.approxPolyDP(c, 0.04 * peri, True)
```

```
OpenCV shape detection
14        # if the shape is a triangle, it will have 3 vertices
15        if len(approx) == 3:
16            shape = "triangle"
17
18        # if the shape has 4 vertices, it is either a square or
19        # a rectangle
20        elif len(approx) == 4:
21            # compute the bounding box of the contour and use the
22            # bounding box to compute the aspect ratio
23            (x, y, w, h) = cv2.boundingRect(approx)
24            ar = w / float(h)
25
26            # a square will have an aspect ratio that is approximately
27            # equal to one, otherwise, the shape is a rectangle
28            shape = "square" if ar >= 0.95 and ar <= 1.05 else "rectangle"
29
30        # if the shape is a pentagon, it will have 5 vertices
31        elif len(approx) == 5:
32            shape = "pentagon"
33
34        # otherwise, we assume the shape is a circle
35        else:
36            shape = "circle"
37
38        # return the name of the shape
39        return shape
```

## Shape detection with OpenCV

Now that our `ShapeDetector` class has been defined, let's create the `detect_shapes.py` driver script:

```
OpenCV shape detection Python
1 # import the necessary packages
2 from pyimagesearch.shapedetector import ShapeDetector
3 import argparse
4 import imutils
5 import cv2
6
7 # construct the argument parse and parse the arguments
8 ap = argparse.ArgumentParser()
9 ap.add_argument("-i", "--image", required=True,
10               help="path to the input image")
11 args = vars(ap.parse_args())
```

Next up, let's pre-process our image:

```
OpenCV shape detection Python
13 # load the image and resize it to a smaller factor so that
14 # the shapes can be approximated better
15 image = cv2.imread(args["image"])
16 resized = imutils.resize(image, width=300)
17 ratio = image.shape[0] / float(resized.shape[0])
18
19 # convert the resized image to grayscale, blur it slightly,
20 # and threshold it
21 gray = cv2.cvtColor(resized, cv2.COLOR_BGR2GRAY)
22 blurred = cv2.GaussianBlur(gray, (5, 5), 0)
23 thresh = cv2.threshold(blurred, 60, 255, cv2.THRESH_BINARY)[1]
24
25 # find contours in the thresholded image and initialize the
26 # shape detector
27 cnts = cv2.findContours(thresh.copy(), cv2.RETR_EXTERNAL,
28                       cv2.CHAIN_APPROX_SIMPLE)
29 cnts = cnts[0] if imutils.is_cv2() else cnts[1]
30 sd = ShapeDetector()
```

The last step is to identify each of the contours:

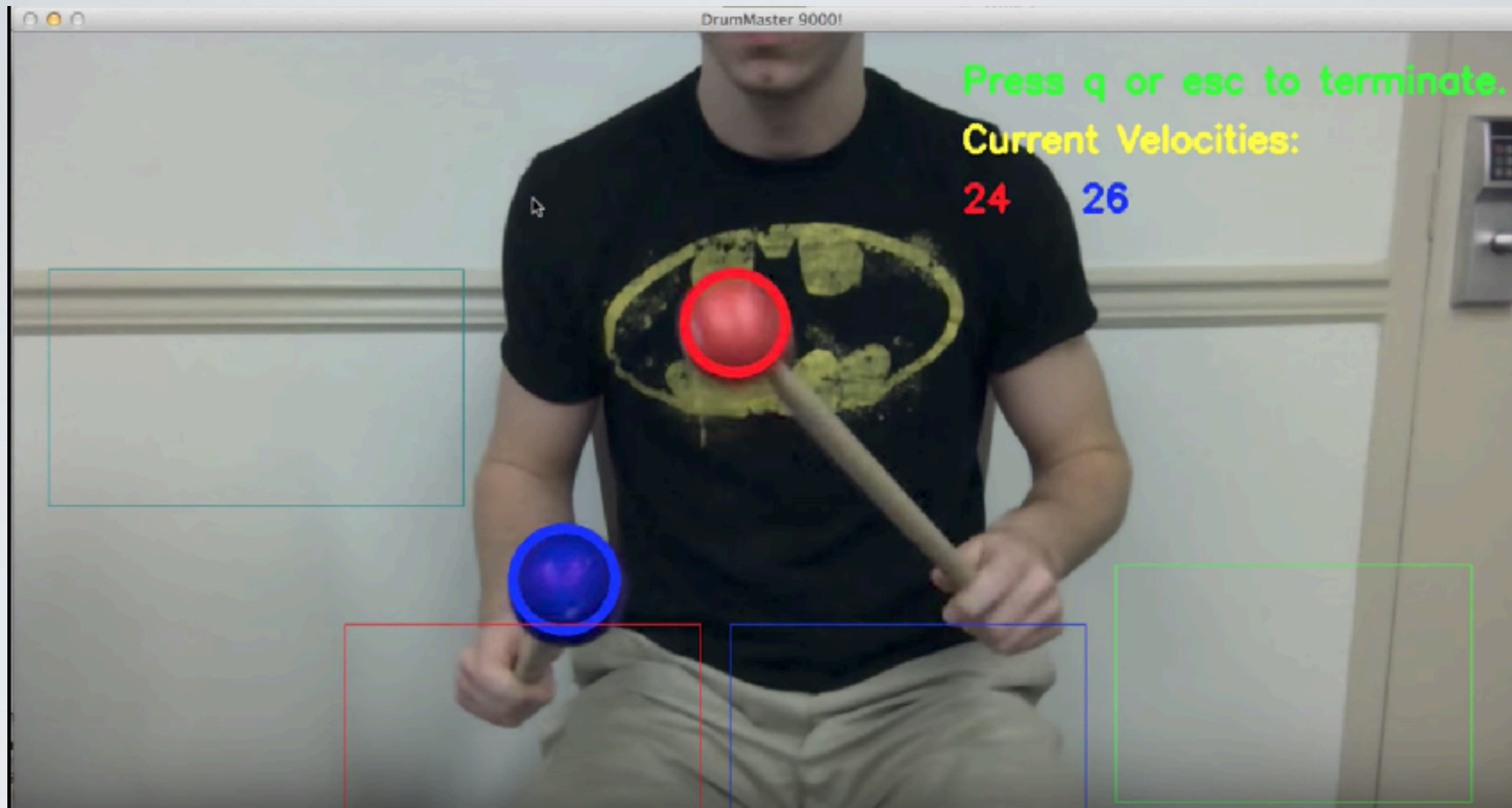
```
OpenCV shape detection Python
32 # loop over the contours
33 for c in cnts:
34     # compute the center of the contour, then detect the name of the
35     # shape using only the contour
36     M = cv2.moments(c)
37     cX = int((M["m10"] / M["m00"]) * ratio)
38     cY = int((M["m01"] / M["m00"]) * ratio)
39     shape = sd.detect(c)
40
41     # multiply the contour (x, y)-coordinates by the resize ratio,
42     # then draw the contours and the name of the shape on the image
43     c = c.astype("float")
44     c *= ratio
45     c = c.astype("int")
46     cv2.drawContours(image, [c], -1, (0, 255, 0), 2)
47     cv2.putText(image, shape, (cX, cY), cv2.FONT_HERSHEY_SIMPLEX,
48               0.5, (255, 255, 255), 2)
49
50 # show the output image
51 cv2.imshow("Image", image)
52 cv2.waitKey(0)
```



- Define the `pyimagesearch` module first. Inside this module we have `shapedetector.py` which will store the implementation of the `ShapeDetector` class.
- Finally we have the `detect_shapes.py` driver script that we'll use to load an image from disk, analyze it for shapes, and then perform shape detection and identification via the `ShapeDetector` class.

# SOUND

Pygame




# AIR DRUMS

<https://www.youtube.com/watch?v=MAnWwxTjL3k>



# PYGAME

A third party library for python dedicated to easy game development.

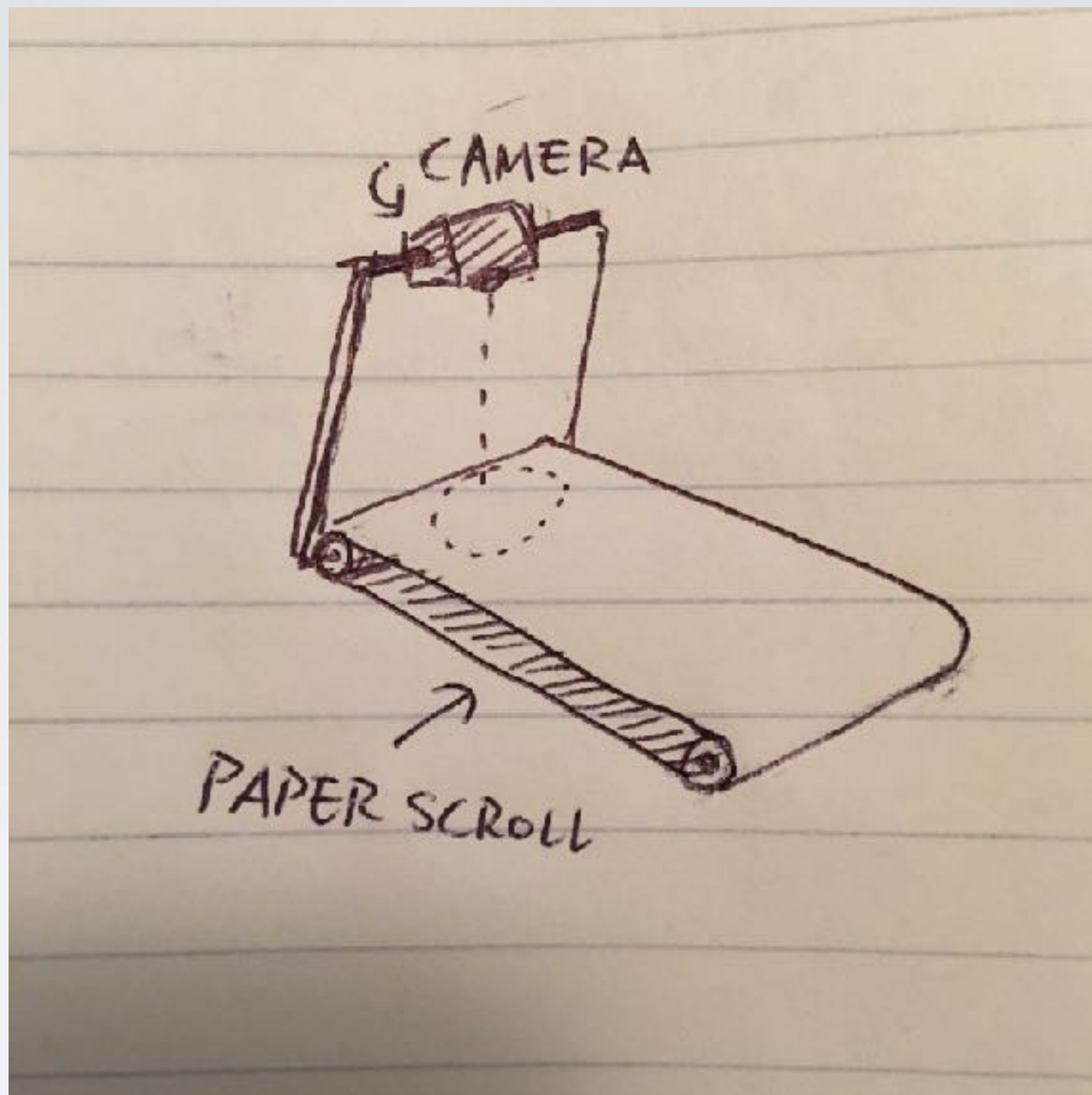
pip install  Projects ▾ News About Getting

## GettingStarted — wiki

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# PROJECT USAGE

- An art installation that offer an interactive experience with audiences.
- A tool for musician to write music.



THANK YOU!