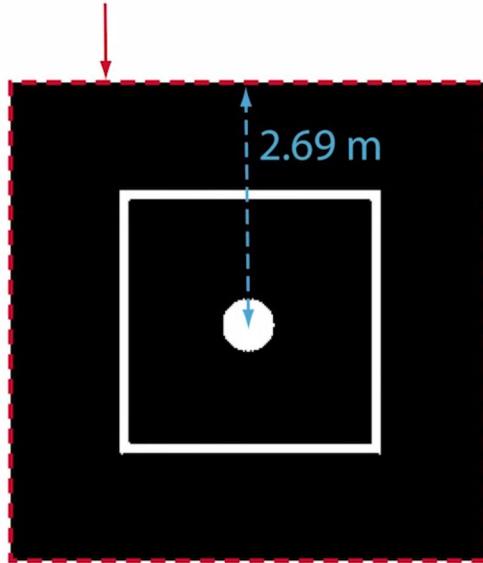
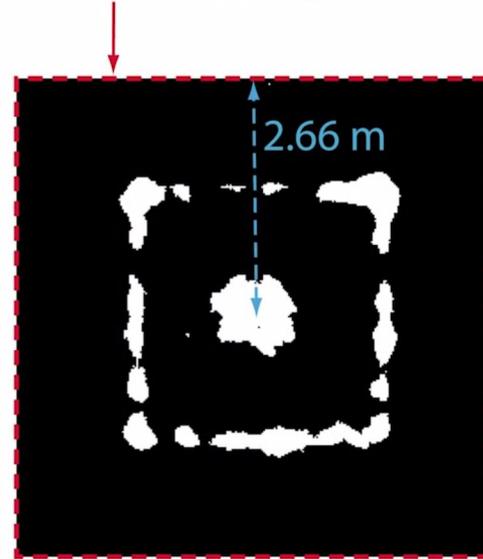


# X-Ray Vision with WiFi

ORIGINAL 5.4m x 5.4m AREA  
COMPLETELY UNKNOWN



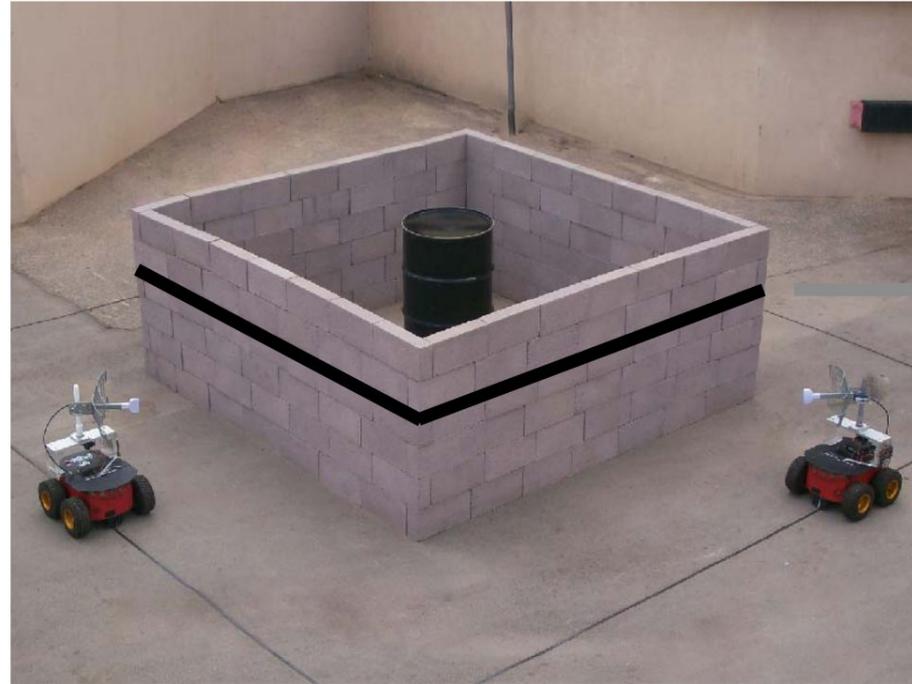
IMAGING RESULT WITH  
1.79% MEASUREMENTS



George Baier  
Art 185GL - S17

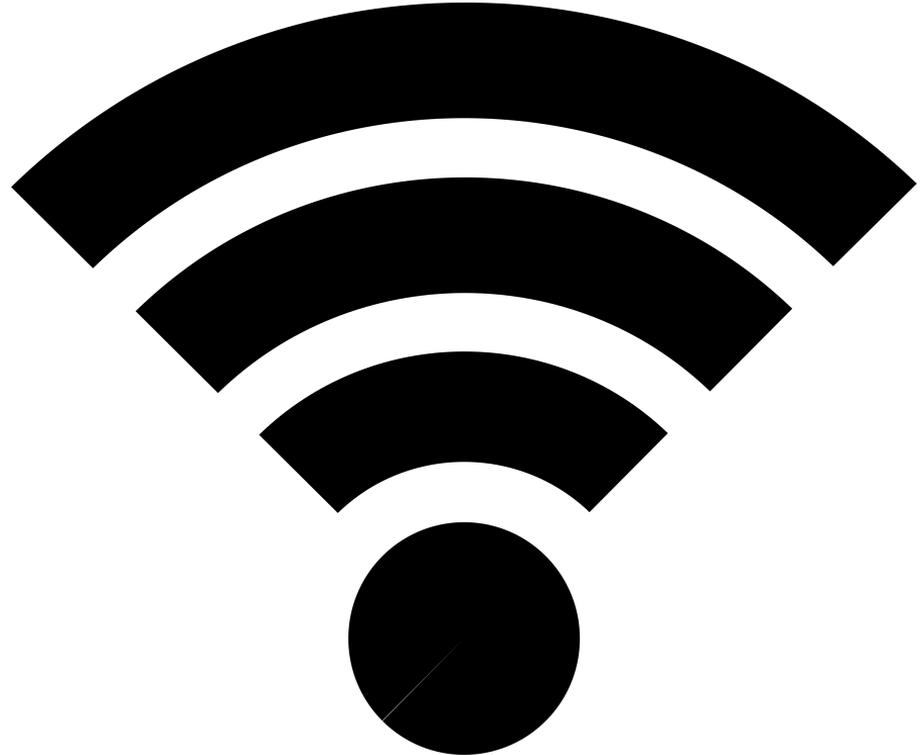
# Overview

- WiFi
- Math
- Robots
- Experiment
- Results
- Future Uses



# WiFi

- What is it?
  - Institute of Electrical and Electronics Engineers (IEEE) 802.11 standards
  - 2.4GHz
- How does it work?
  - Transmitter
  - Receiver
  - Waves (3-5 inches crest to trough)
  - Crest = 1
  - Trough = 0

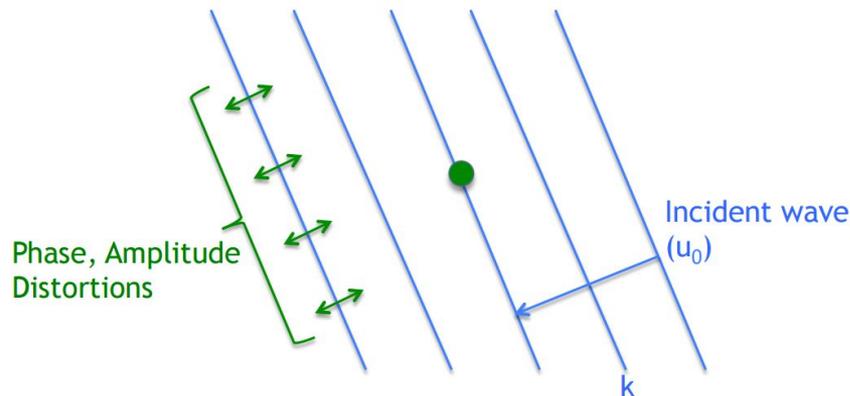


# Math

$$u = e^{i(kz - \omega t)} e^{\Xi(\mathbf{x}_\perp, z, \omega)}$$

$$\Xi(x_\perp, Z, \omega) = \frac{k^2}{2\pi^2} \int_0^Z \iint \tilde{G}(k_\perp, Z - z, \omega) \xi(k_\perp, z) e^{-ik_\perp x_\perp} dk_\perp dz$$

- Rytov Approximation
  - Linearization
  - Scattering
  - Filter
  - Imaging based on received signal power
- Line of Sight (LOS) Approximation
  - Integral of line joining the positions of the transmitter and receiver



$$P_r(\mathbf{r})(\text{dBm}) = P_{\text{inc}}(\mathbf{r})(\text{dBm}) - 10 \log_{10}(e^{-2}) \omega \int_{\mathbb{L}_T \rightarrow R} \text{Imag}(\alpha(\mathbf{r}')) dr'$$

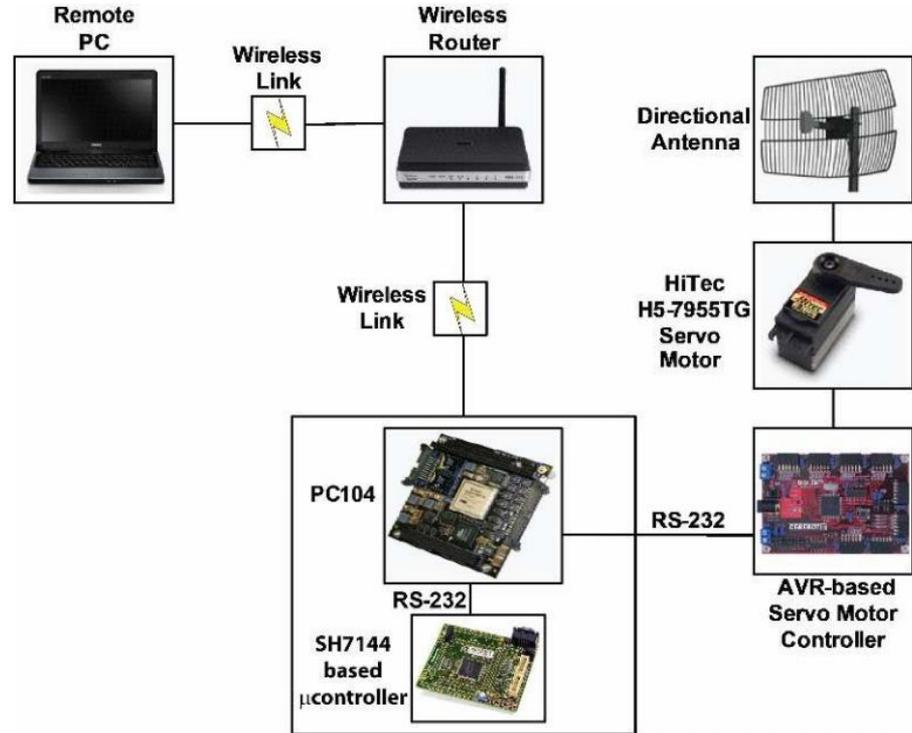
# Robots

- Components
  - Pioneer 3-AT mobile robots
  - Onboard PC
  - IEEE 802.11g (WLAN) card
  - Renesas SH7144-based micro-controller
    - Motors
    - Actuators
    - Sensors
      - Gyroscopes
      - Encoders
  - Directional antennas
  - Digilent Cerebot II micro-controller
  - Hitec HA-7955TG digital servo
  - D-Link WBR-1310 wireless router



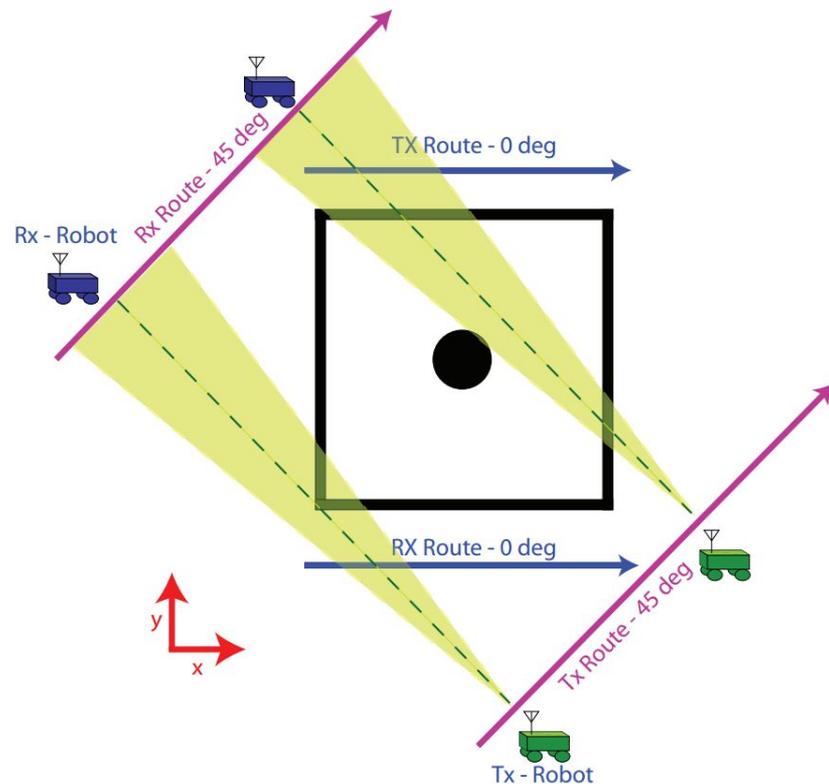
# Robots

- Code
  - C++ using the ARIA library
  - four separate in-software threads
    - antenna control
    - signal strength
    - motor control
    - main thread
  - designed for autonomy and precision



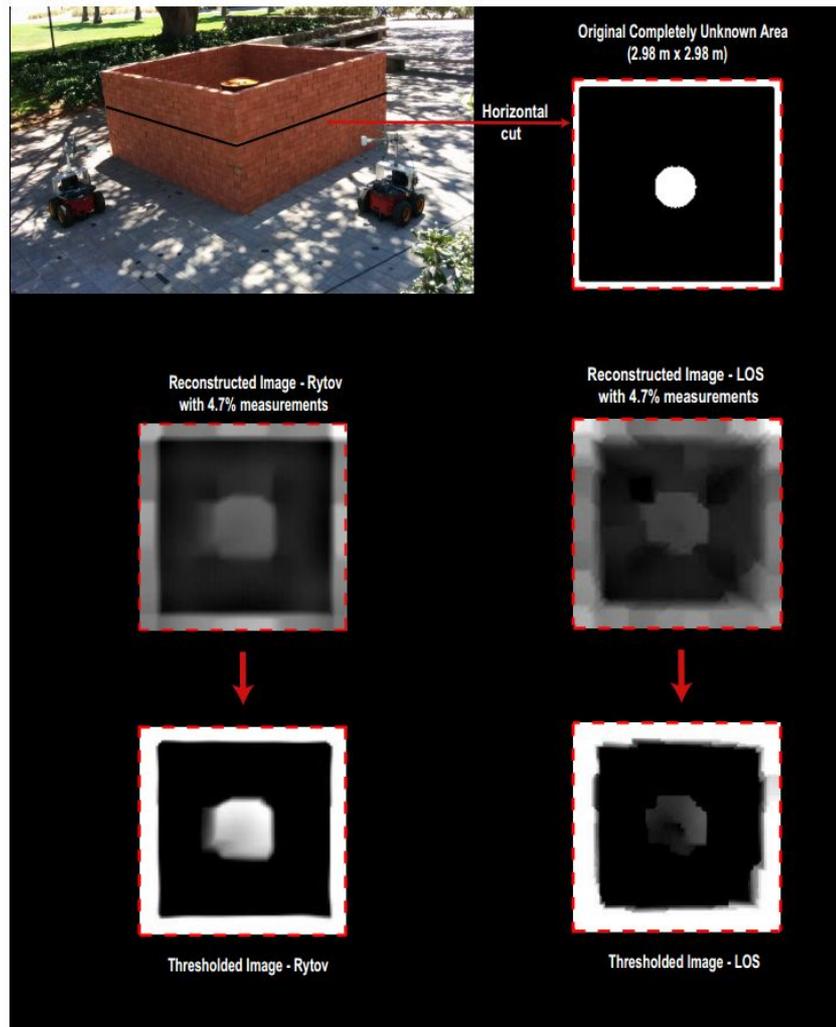
# Experiment

- 4 passes
  - Vertical
  - Horizontal
  - 45 degrees
  - 135 degrees
- Parallel Routes
- Record signal strength
- Apply Rytov and LOS approximations



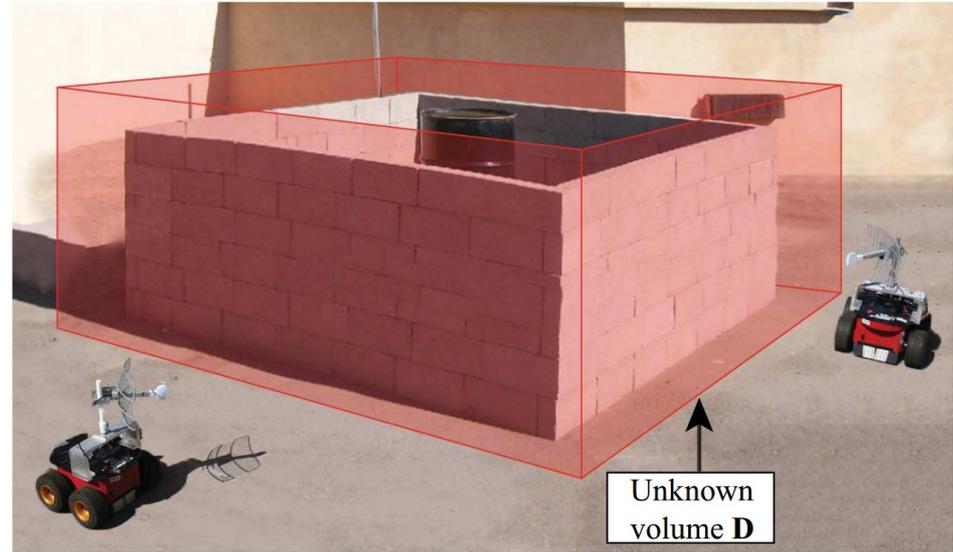
# Results

- 4.7% of signal measured
- Rytov outperforms LOS
- Thresholding applied to images
- Rytov faster than LOS
- Errors
  - Route Length
  - Antenna Misalignment



# Summary

- WiFi
- Math
- Robots
- Experiment
- Results
- Future Uses
  - Search and Rescue
  - Tracking the elderly



Questions?

# Sources

[http://www.ece.ucsb.edu/~ymostofi/papers/TVT15\\_DepatlaBucklandMostofi.pdf](http://www.ece.ucsb.edu/~ymostofi/papers/TVT15_DepatlaBucklandMostofi.pdf)

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